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Presentation Title : Breaking the DP rules – Doing things differently with autonomous vessels

Abstract: Dynamic Positioning systems are comprised of sensors, a control system and thrusters which allow a vessel to hold position or move in a controlled fashion. They have a set of rules that govern how they work and how sub-systems and operators interact.

Autonomous vessels also have sensors, a control system and a set of thrusters. We will look at which of the DP rules we have continued to follow in the design of autonomous or semi-autonomous solutions and which we have broken and why.

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This e-mail was sent from a abstract form that was submitted on Dynamic Positioning Committee website (<http://dynamic-positioning.com/>)